

Analytic error control methods for rotation in Ambisonics

鄭任傑

Outline

- ▶ Motivation
- ▶ Ambisonics
- ▶ Rotation in Ambisonics
- ▶ Conclusion

Motivation

- ▶ Build a theory for spatial audio that is channel agnostic, homogeneous and coherent, but also has good localization with few channels.

Spatial Audio Techniques

- ▶ Channel-based: the whole encoding/decoding and recording/reproduction is based on a specific channel layout, e.g. 2.0, 5.1, 7.1, ..., Auro3D, Hamasaki 22.2.
- ▶ Layout-independent (channel-agnostic): the recording and encoding format is independent from the reproduction layout (includes sound field reconstruction methods and object-based formats). e.g. Ambisonics.

Ambisonics

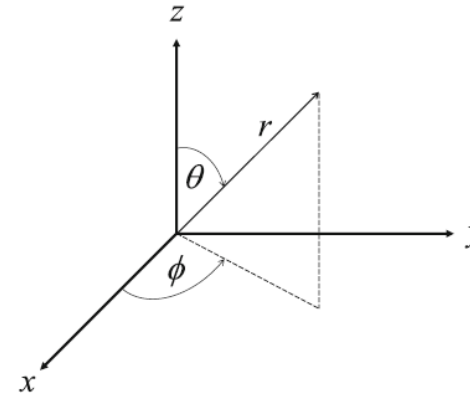
- ▶ Ambisonics comprises both encoding, recording and reproduction (decoding) techniques that can be used live or in studio to present a 2-dimensional (planar, or horizontal-only) or 3-dimensional (periphonic, or full-sphere) sound field.
- ▶ Ambisonics encoding of the sound field which based on the acoustic wave equation and its accurate reconstruction in a point in space.

The Acoustic Wave Equation

$$\nabla^2 p(., t) - \frac{1}{c} \frac{\partial^2}{\partial t^2} p(., t) = 0$$

where ∇^2 is Laplacian in spherical coordinates $f(r, \theta, \phi)$

$$\nabla^2 f \equiv \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$$



- The solution of the PDE is the spherical harmonics

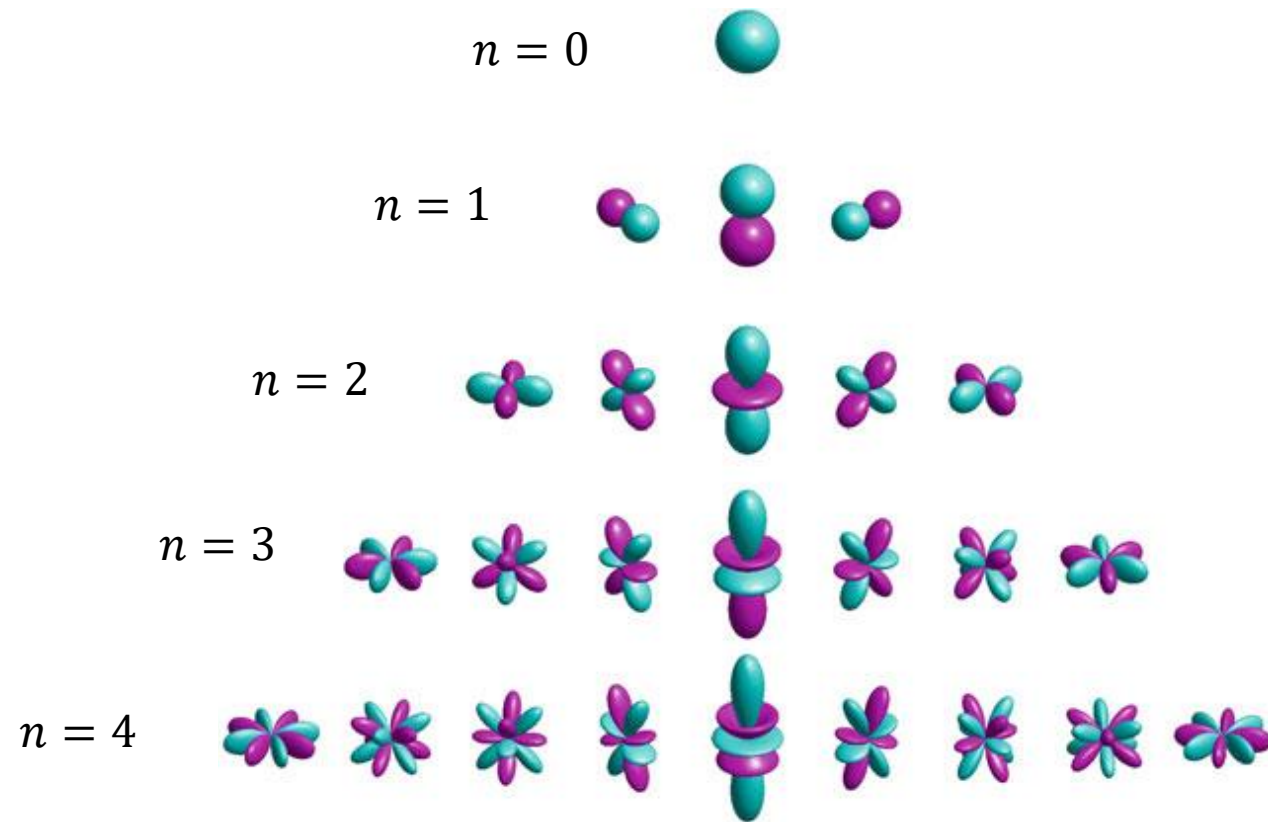
$$Y_n^m(\theta, \phi) = \sqrt{\frac{2n+1}{4\pi} \frac{(n-m)!}{(n+m)!}} P_n^m(\cos \theta) e^{im\phi}$$

where n is the order of the spherical harmonics

Spherical Harmonics

$n = 0$	$Y_0^0(\theta, \phi) = \sqrt{\frac{1}{4\pi}}$
$n = 1$	$Y_1^{-1}(\theta, \phi) = \sqrt{\frac{3}{8\pi}} \sin \theta e^{-i\phi}$
	$Y_1^0(\theta, \phi) = \sqrt{\frac{3}{4\pi}} \cos \theta$
	$Y_1^1(\theta, \phi) = -\sqrt{\frac{3}{8\pi}} \sin \theta e^{i\phi}$
$n = 2$	$Y_2^{-2}(\theta, \phi) = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{-2i\phi}$
	$Y_2^{-1}(\theta, \phi) = \sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{-i\phi}$
	$Y_2^0(\theta, \phi) = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1)$
	$Y_2^1(\theta, \phi) = -\sqrt{\frac{15}{8\pi}} \sin \theta \cos \theta e^{i\phi}$
	$Y_2^2(\theta, \phi) = \sqrt{\frac{15}{32\pi}} \sin^2 \theta e^{2i\phi}$

Spherical Harmonics



Spherical Fourier Transform

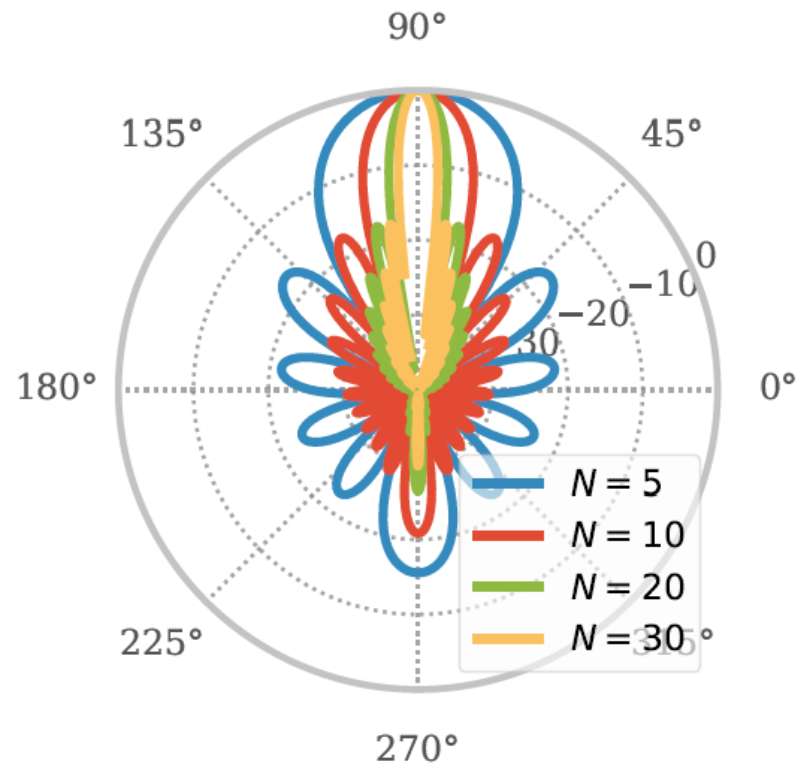
- ▶ The set of spherical harmonics $Y_n^m(\theta, \phi)$, for $n \geq 0$ and $-n \leq m \leq n$, can be used to compose a wide range of functions on the sphere.
- ▶ It also be called Ambisonics representation or encoding higher order Ambisonics.

$$f(\theta, \phi) = \sum_{n=0}^{\infty} \sum_{m=-n}^n f_{n,m} Y_n^m(\theta, \phi)$$

- ▶ inverse spherical Fourier transform or decoding higher order Ambisonics.

$$f_{n,m} = \int f(\theta, \phi) [Y_n^m(\theta, \phi)]^* d\Omega$$

SH Representation Plot



Head rotation in SH domain

- ▶ rotation matrix

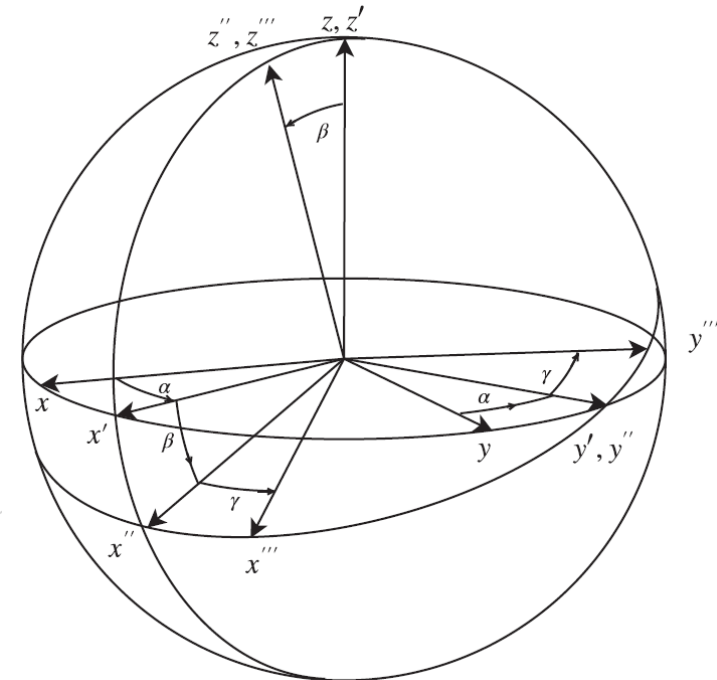
$$\hat{g} = \hat{u}(\alpha)\hat{a}(\beta)\hat{u}(\gamma) = \begin{bmatrix} \cos\alpha & \sin\alpha & 0 \\ -\sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos\beta & 0 & -\sin\beta \\ 0 & 1 & 0 \\ \sin\beta & 0 & \cos\beta \end{bmatrix} \begin{bmatrix} \cos\gamma & \sin\gamma & 0 \\ -\sin\gamma & \cos\gamma & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$f'_{n,m} = \sum_{m'=-n}^n f_{n,m'} \mathcal{D}_{m',m}^n$$

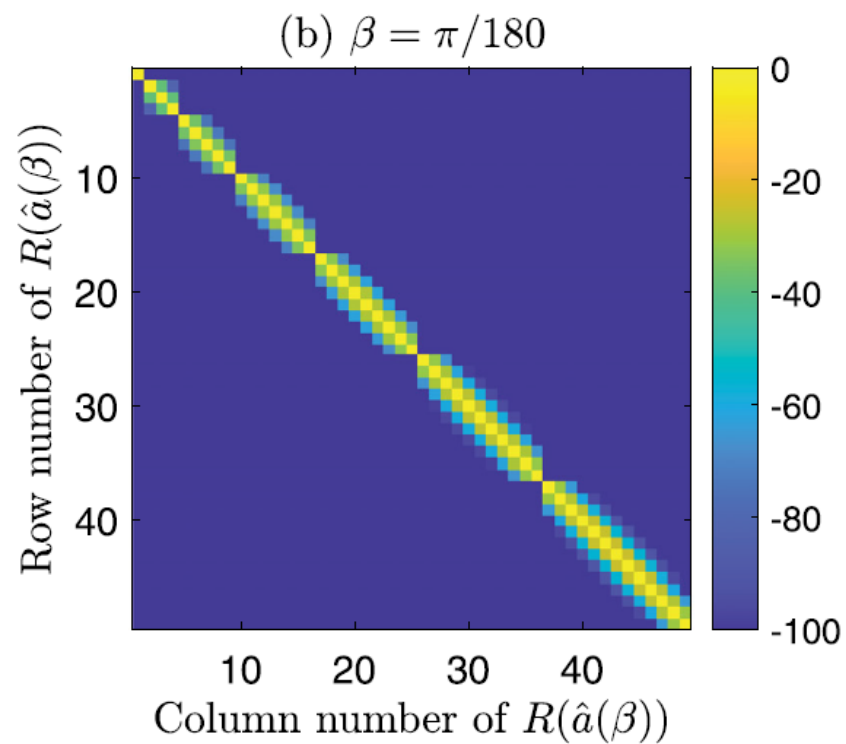
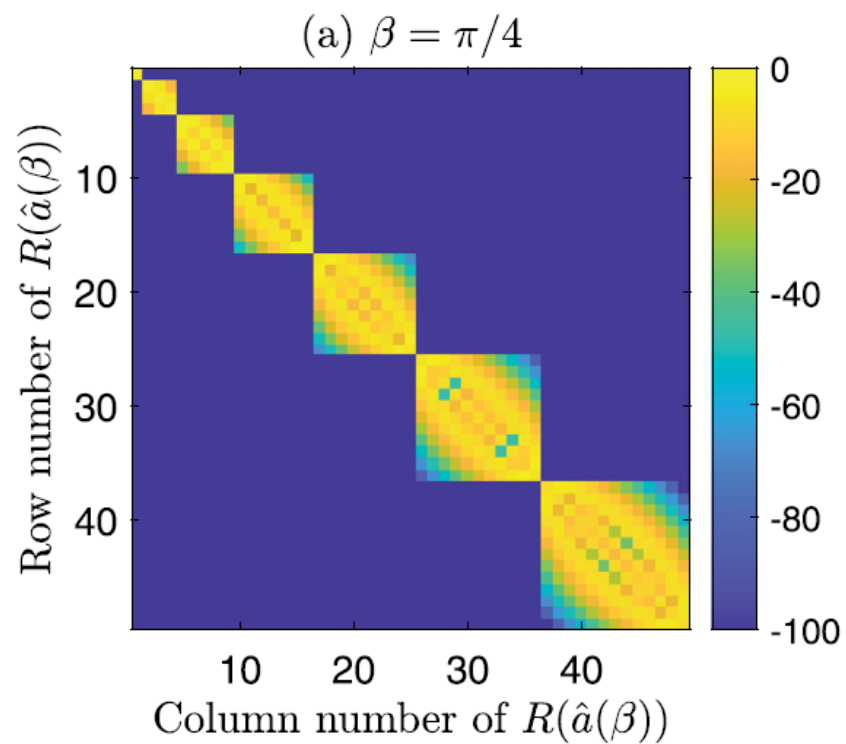
where $\mathcal{D}_{m',m}^n$ is the element of Wigner D-matrix.

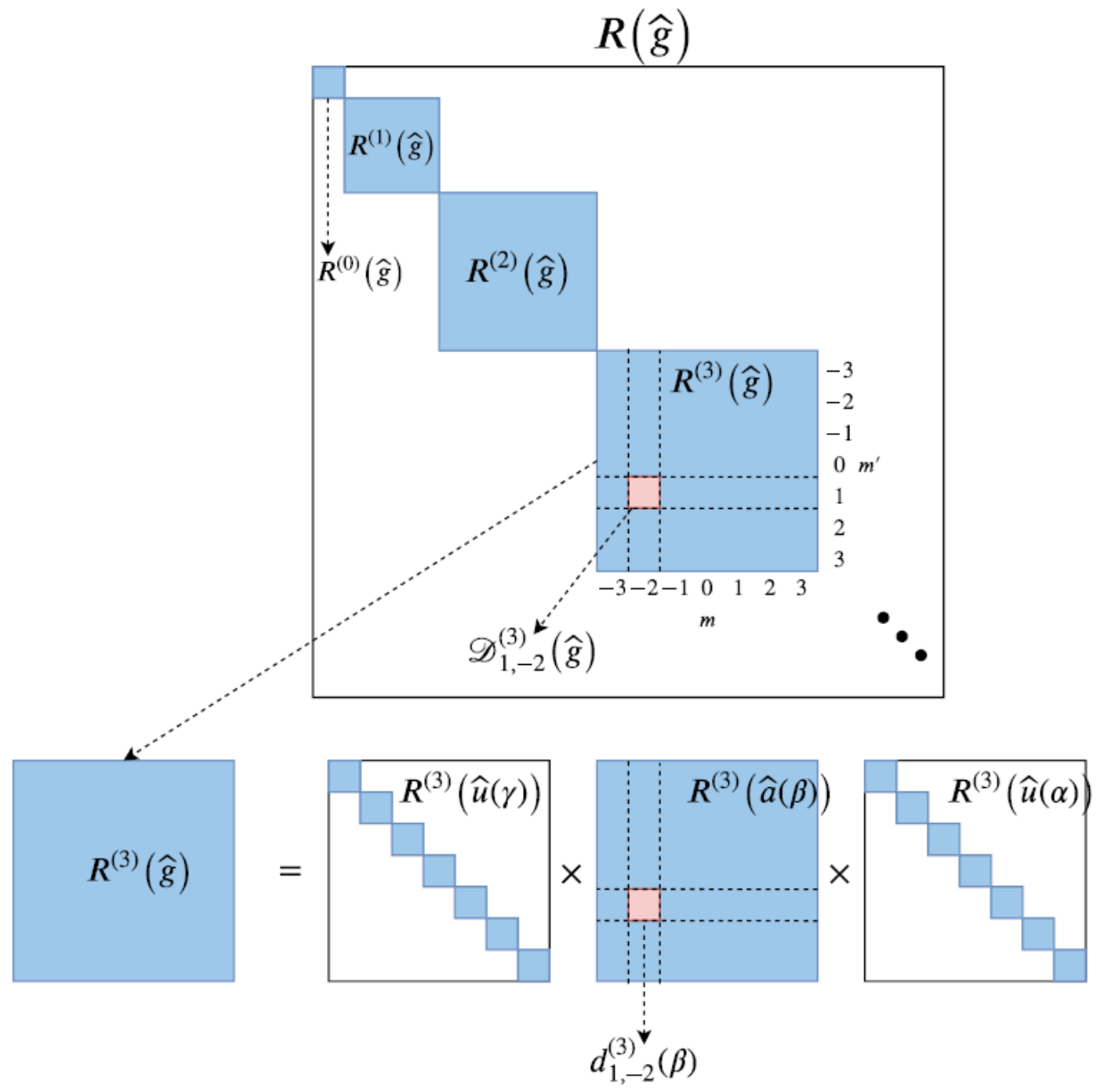
$$\mathcal{D}_{m',m}^n = e^{im'\gamma} d_{m',m}^n(\beta) e^{ima}$$

where $d_{m',m}^n$ is the element of Wigner's (small) d-matrix.



Magnitudes of WdMs





$$\begin{array}{c}
 R(\hat{a}(\beta)) \\
 \begin{array}{c}
 R^{(1)}(\hat{a}(\beta)) \\
 R^{(0)}(\hat{a}(\beta)) \quad R^{(2)}(\hat{a}(\beta)) \\
 R^{(3)}(\hat{a}(\beta)) \\
 \dots
 \end{array}
 \end{array}$$

$$R^{(3)}(\hat{a}(\beta)) = I + i\beta J_y^{(3)} - \frac{\beta^2}{2!} [J_y^{(3)}]^2 - \frac{i\beta^3}{3!} [J_y^{(3)}]^3 + \dots$$

Conclusion

Ambisonics provide

- ▶ Nice physical formulation
- ▶ Reproduce the sound field
- ▶ Getting a lot of application in Augmented/Virtual Reality (AR/VR)

Reference

1. T. Magariyachi and Y. Mitsufuji, “Analytic error control methods for efficient rotation in dynamic binaural rendering of Ambisonics,” *The Journal of the Acoustical Society of America*, vol. 147, no. 1, pp. 218-230, 2020.
2. C. Hold, H. Gamper, V. Pulkki, N. Raghuvanshi, and I. J. Tashev, “Improving Binaural Ambisonics Decoding by Spherical Harmonics Domain Tapering and Coloration Compensation,” *ICASSP 2019 - 2019 IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP)*, 2019.
3. B. Rafaely, “Analysis and design of spherical microphone arrays,” *IEEE Transactions on Speech and Audio Processing*, vol. 13, no. 1, pp. 135-143, 2005.
4. B. Rafaely, *Fundamentals of Spherical Array Processing*. Cham: Springer International Publishing, 2019.